

Spatial Gesture Semantics

1. Introduction: Visuo-Spatial Level of Meaning

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Basic Information

1. Introduction: Visuo-spatial Level of Meaning
2. Spatial Gesture Semantics
3. Exemplification and Informational Evaluation
4. AI and Gesture Detection
5. Frame-based Speech–Gesture Integration

Andy Lücking

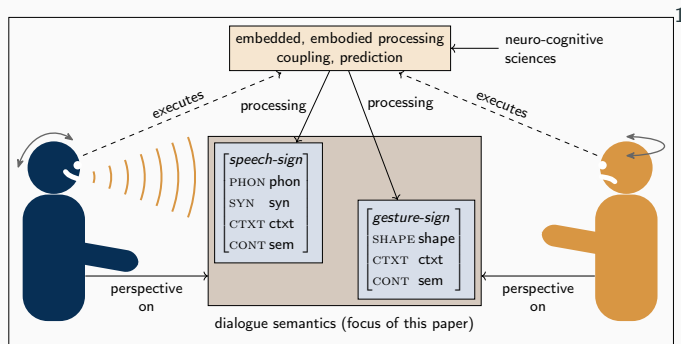
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Multimodal Dialogue



Dialogue: research topic
sui generis

- interaction
- “polyphony”
- alignment
- verbal and non-verbal signals

¹ A. Lücking and J. Ginzburg (2023). “Leading voices: Dialogue semantics, cognitive science, and the polyphonic structure of multimodal interaction”. In: [Language and Cognition](#) 15, 148–172

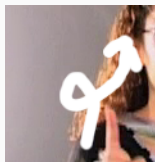
Overview of nonverbal communication means²

- paralinguistic signals / speech phonation
- laughter, sighing / non-speech phonation
- **manual gesture** (our focus)
- facial expressions
- gaze
- proxemics: spatio-social behavior connected to the interpersonal distances of interlocutors.
- tactile codes
- time behaviour (“chronemics”): length of laughter, respiratory pauses; “kaireemics”: at the right moment
- ~~Others, hitherto not much studied: clothing, smelling, ...~~

²From A. Lücking and T. Pfeiffer (2012). “Framing Multimodal Technical Communication. With Focal Points in Speech-Gesture-Integration and Gaze Recognition”. In: [Handbook of Technical Communication](#). Ed. by A. Mehler and L. Romary. In collab. with D. Gibbon, 591–644

Why gesture?

- Gesture can add meaning:



- “Ich g[laube das  sollen TREP]pen sein” /

I think that should be staircases

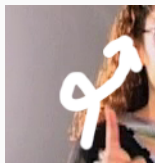
(Capitalization indicates main stress of the first syllable of the noun *Treppen* ‘staircases’, square brackets indicate the temporal alignment of speech and gesture)

- Obligatory pointing gestures: *I want to have this!*

³ P. Schlenker (2018). “Gesture projection and cosuppositions”. In: [Linguistics and Philosophy](#) 41, 295–365, 296

Why gesture?

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(Capitalization indicates main stress of the first syllable of the noun *Treppen* ‘staircases’, square brackets indicate the temporal alignment of speech and gesture)

- Obligatory pointing gestures: *I want to have this!*

- But what exactly is the semantic contribution of a gesture?
- Semantic lacuna: “It should be emphasized that we will not seek to explain how a gesture [...] comes to have the content that it does.”³
- ➔ truth-conditional visuo-spatial meaning
- ➔ theoretically challenging: informational evaluation (exemplification)

³ P. Schlenker (2018). “Gesture projection and cosuppositions”. In: [Linguistics and Philosophy](#) 41, 295–365, 296

- Gesture studies
- Dynamic semantics
- Grammar theory
- Computer Science
- Model-theoretic semantics
- Philosophy of language
- Cognitive Science / Psychophysics

⁴ A. Lücking (11, 2013). [Eclectic Semantics for Non-Verbal Signs](#). Talk at the Conference on Investigating Semantics: Empirical and Philosophical Approaches, Bochum

On gestures and gestures

- (1) Stewart Robson on *ESPN FC Extra Time*
(first gesture):

You know when they go on that wheel



*and throw the dagger would you
ever like to see that go wrong?*

⇒ the wheel has a circular layout

(https://www.youtube.com/watch?v=CiVS5_HKFY8&t=0h1m18s)

Ex: Wheel

- (1) Stewart Robson on *ESPN FC Extra Time*
(first gesture):

You know when they go on that wheel



*and throw the dagger would you
ever like to see that go wrong?*

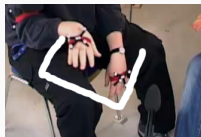
⇒ the wheel has a circular layout

(https://www.youtube.com/watch?v=CiVS5_HKFY8&t=0h1m18s)

⇒ Hand is drawing a shape

Ex: Like this

- (2) SaGA dialogue V11, starting at 2:32:
dann ist das Haus halt so: / *then the house is*

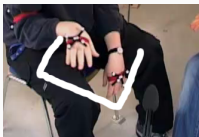


like this:

⇒ the house has a rectangular, U-shaped layout.

Ex: Like this

- (2) SaGA dialogue V11, starting at 2:32:
dann ist das Haus halt so: / *then the house is*



like this:

⇒ the house has a rectangular, U-shaped layout.

⇒ Again, shape drawing

- (3) SaGA dialogue V5, starting at 6:48
und da musst du sofort, scharfer rechter



Winkel, rechts rein /
*and you must enter immediately on the right,
at an acute right angle*

⇒ the path of the movement runs straight to
the right

- (3) SaGA dialogue V5, starting at 6:48
und da musst du sofort, scharfer rechter



Winkel, rechts rein /
*and you must enter immediately on the right,
at an acute right angle*

⇒ the path of the movement runs straight to
the right

⇒ pointing/drawing a direction

(4) Keanu Reeves at the *Graham Norton Show*:



a car pulled out in front of me

⇒ the car pulled out in a straight line from the right

(https://www.youtube.com/watch?v=6VxnceG_eh4&t=0h13m39s)

~> Hand draws movement trajectory, from speaker's perspective + represents car

- (5) Etienne Gardet:
Was mich wundert is, es gibt ja beim Tennis



so Röhren, ich weiß nich ob
ihr die kennt / *What surprises me is that there
are such tubes in tennis, I don't know if you
know them*

(<https://www.youtube.com/watch?v=1xLPdMU91F8&t=1h23m42s>)

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(<https://www.youtube.com/watch?v=1xLPdMU91F8&t=1h23m42s>)

↪ Hands holding/sculpturing a
cylindric volume

- (6) Stewart Robson on *ESPN FC Extra Time*
(second gesture):
You know when they go on that wheel and



*throw the dagger would you ever
like to see that go wrong?*

⇒ throwing exhibits a certain handshape and
movement trajectory

(https://www.youtube.com/watch?v=CiVS5_HKFY8&t=0h1m18s)

- (6) Stewart Robson on *ESPN FC Extra Time*
(second gesture):
You know when they go on that wheel and



throw the dagger would you ever \rightsquigarrow Speaker mimes throwing action
like to see that go wrong?

\Rightarrow throwing exhibits a certain handshape and
movement trajectory

(https://www.youtube.com/watch?v=CiVS5_HKFY8&t=0h1m18s)

(7) Keanu Reeves at the *Graham Norton Show*:



no one could hit

⇒ fist and straight movement path away from speaker's body

(https://www.youtube.com/watch?v=6VxnceG_eh4&t=0h1m6s)

(7) Keanu Reeves at the *Graham Norton Show*:



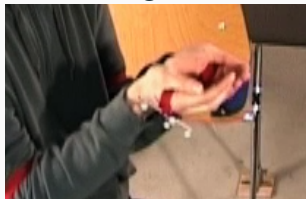
no one could hit

⇒ fist and straight movement path away from speaker's body

(https://www.youtube.com/watch?v=6VxnceG_eh4&t=0h1m6s)

≈> Speaker mimes hitting action

(8) SaGA dialogue V21, starting at 4:38:

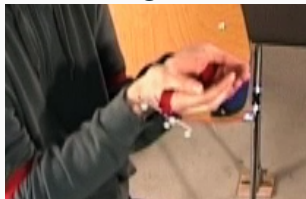


und 'ne kleinere Schale obendrauf /

and a smaller bowl on top

⇒ layout of hands represents main axis of
bowl object

- (8) SaGA dialogue V21, starting at 4:38:



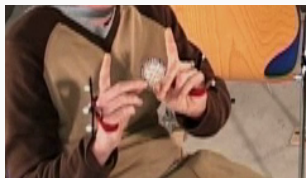
~> Hands represent object talked about

und 'ne kleinere Schale obendrauf /
and a smaller bowl on top

⇒ layout of hands represents main axis of
bowl object

Ex: Two towers

(9) SaGA dialogue V24, 6:25:

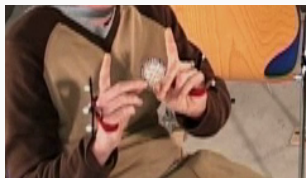


die rechte Kirche die hat zwei spitze Türme /
*the church to the right it has two pointed
towers*

⇒ Church towers are stretched vertically

Ex: Two towers

(9) SaGA dialogue V24, 6:25:



↪ Each index finger represents a church tower

die rechte Kirche die hat zwei spitze Türme /
*the church to the right it has two pointed
towers*

⇒ Church towers are stretched vertically

Ex: Some ...some

(10) Daniel Levitin, *Ted talk*:



some of them are obvious
some of them are not so obvious



⇒ *on the one hand...on the other hand* figure
(<https://www.youtube.com/watch?v=8jPQjjsBbIc&t=0h3m55s>)

Ex: Some ...some

(10) Daniel Levitin, *Ted talk*:



some of them are obvious
some of them are not so obvious



~> Hands engage in discourse structuring

⇒ *on the one hand...on the other hand* figure
(<https://www.youtube.com/watch?v=8jPQjjsBbIc&t=0h3m55s>)

(11) Kathy Griffin:⁵



Anyway um .. so so then

decided to promote my own shows

⇒ palm up open hand gesture towards Colbert (host on the right) shows “re-engagement with main discourse” (*op. cit.*, p. 177f)

([https:](https://www.youtube.com/watch?v=UWKIljRfl1tM&t=0h7m17s)

[//www.youtube.com/watch?v=UWKIljRfl1tM&t=0h7m17s](https://www.youtube.com/watch?v=UWKIljRfl1tM&t=0h7m17s))

⁵Slightly simplified from S. Laparle (2022). “The shape of discourse: how gesture structures conversation”. PhD thesis. University of California, Berkeley, p. 177

Thumbs Up

(12)



Male Hand Giving Thumbs Up Sign by
freebie.photography, CC BY 3.0 Unported.

⇒ emblem: *good/like*

(12)



Male Hand Giving Thumbs Up Sign by
freebie.photography, CC BY 3.0 Unported.

⇒ emblem: *good/like*

↪ Conventionalized response item

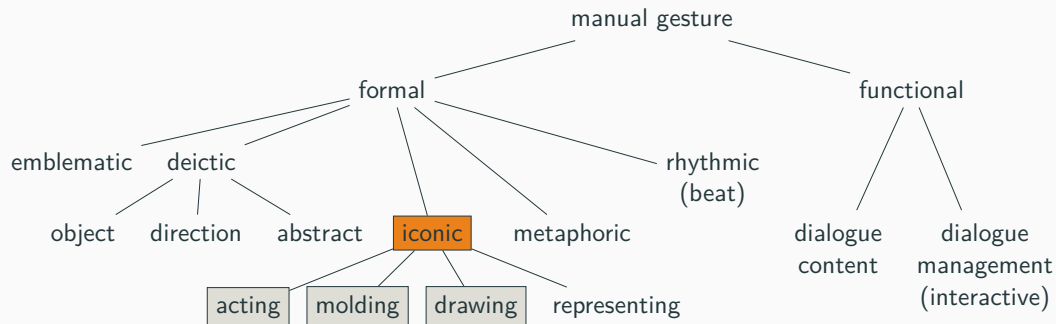
Different iconic motivations of gestures

Acting, molding, drawing, representing

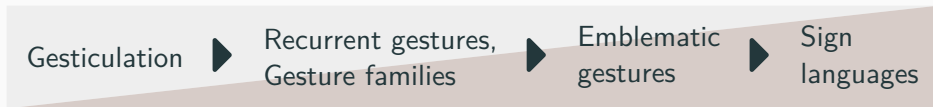
“Müller [...] has distinguished four modes of representation: **acting**, **molding**, **drawing**, and **representing**. In the **acting** mode, the hands are used to mime or reenact actual manual activities, such as grasping, holding, giving, receiving, opening a window, turning off a radiator, or pulling an old-fashioned gear shift; in the **molding** mode, the hands mold or shape a transient sculpture, such as a picture frame or a bowl; in the **drawing** mode, the hand(s) outline(s) the contour or the form of objects or the path of movements in space; and in the **representing** mode, the hand embodies an object as a whole, a kind of manual ‘sculpture’, when, for example, a flat open hand represents a piece of paper and the extended index finger represents the pen used to make notes on that paper.” (p. 1691)⁶

⁶ C. Müller (2014). “Gestural modes of representation as techniques of depiction”. In: **Body – Language – Communication**. Ed. by C. Müller et al. Vol. 2, 1687–1702

Dimensions of classifying gestures



Kendon's Continuum⁷, modified



- To the right: increasing degree of conventionalization, decreasing language dependency
- We are concerned with Gesticulation and recurrent gestures
- Problem: no lexicon (as exist for emblems and sign language)

⁷ D. McNeill (1992). [Hand and Mind. What Gestures Reveal about Thought](#). Cambridge UP, 37

- A gesture attaches to a “docking point” in speech, the **affiliate**⁸
- Hints: Temporal alignment, stressed intonation/information structure, semantic constraints (‘ indicates secondary stress)
- Affiliate is a is a lexical item in about 70% of cases⁹

⁸ E. A. Schegloff (1984). “On some Gestures’ Relation to Talk”. In: **Structures of Social Action. Studies in Conversational Analysis**. Ed. by J. M. Atkinson and J. Heritage, 266–296

⁹ A. Mehler and A. Lücking (2012). “Pathways of Alignment between Gesture and Speech: Assessing Information Transmission in Multimodal Ensembles”. In: **Proc. of the International Workshop on Formal and Computational Approaches to Multimodal Communication under the auspices of ESSLLI 2012**, Opole, Poland, 6-10 August





Scope of spatial gesture semantics

- There are various kinds/uses of gestures
- lack of “gestionary” (gesture lexicon) → we need a ways to interpret a gesture('s form) “online”
- Gestures integrate with (lexical) affiliate
- There is no presupposition that a spatial semantics captures all of them (alike)
- Stroke is assumed to be the semantically relevant gesture phase

Gesture phases



- By 'gesture', we usually refer to the stroke phase
- Preparation often anticipates/precedes the gesture's affiliate → interesting from a production perspective
- typical alignment: co-speech

- **Co:**
I think that should be staircases

- **Pre:**
I think that should be staircases

- **Pro:**
I think that should be

- **Post:**
I think that should be staircases


¹⁰ P. Schlenker (2018). “Gesture projection and cosuppositions”. In: [Linguistics and Philosophy](#) 41, 295–365; T. Slama-Cazacu (1976). “Nonverbal Components in Message Sequence: ‘Mixed Syntax’”. In: [Language and Man. Anthropological Issues](#). Ed. by W. C. McCormick and S. A. Wurm, 217–227

- Co seems to be natural, Pro and Post presumably intentionally produced → pragmatic effects
- Conjecture: Pro works the better the more right on Kendon's continuum (conventionalization)
- Pre found with word elicitation difficulties^a

^a M. L. Rose (2013). "Releasing the Constraints on Aphasia Therapy: The Positive Impact of Gesture and Multimodality Treatments". In: [American Journal of Speech-Language Pathology](#) 22, 227–239

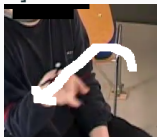
- Sometimes gestures add meaning.
- Often, speech and gesture have seemingly identical meanings.
- “Yet they express this meanings in completely different ways.” (McNeill 1992:11)¹¹

¹¹ D. McNeill (1992). [Hand and Mind. What Gestures Reveal about Thought](#). Cambridge UP

A visuo-spatial level of meaning

Teasing apart verbal and gestural meaning

[Talking about an entrance door]



zwei .. äh .. Stangen mit nem Dach
drüber halt
(*two .. uh .. poles with a roof over them*)

- Intuitively, the gesture just depicts what is said (*over them*)
- **IF** gestures contribute meaning like words do, we would expect that meaning to be addressable.

Interlude: Parallelism constraint

- Clarification request:
categorical and phonological
parallelism with their source¹²
 - A: Do you fear him? B:
Fear? / #Afraid?
 - A: I phoned him. B: Him?
/ #He?
 - A: Were you cycling
yesterday? B: Cycling? /
#Cycled?

¹² J. Ginzburg and R. Cooper (2004). “Clarification, Ellipsis, and the Nature of Contextual Updates in Dialogue”. In: *Linguistics and Philosophy* 27, 297–365

¹³ J. Ginzburg and A. Lücking (2021). “Requesting clarifications with speech and gestures”. In: *Proc. of the 1st Workshop on Multimodal Semantic Representations*, 21–31

Interlude: Parallelism constraint

- Clarification request: categorical and phonological parallelism with their source¹²
 - A: Do you fear him? B: Fear? / #Afraid?
 - A: I phoned him. B: Him? / #He?
 - A: Were you cycling yesterday? B: Cycling? / #Cycled?
- Parallelism constraint generalizes multimodally¹³
 - B: You have to move your legs like this [*moves right hand up and down in a wave-like manner*]. A: [*moves right hand up and down in a wave-like manner, raises eye-brows*] (constructed from a kids TV show)
 - A: I hear you're busy ⟨laughter⟩ [= little giggle]. B: ⟨laughter⟩? (= low arousal laughter with rising contour). (attested example)

¹² J. Ginzburg and R. Cooper (2004). "Clarification, Ellipsis, and the Nature of Contextual Updates in Dialogue". In: *Linguistics and Philosophy* 27, 297–365

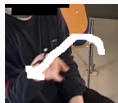
¹³ J. Ginzburg and A. Lücking (2021). "Requesting clarifications with speech and gestures". In: *Proc. of the 1st Workshop on Multimodal Semantic Representations*, 21–31

- Repair: Repetition of (delayed) reparandum ¹⁴
 - A: I think I'll wear my green dress. Can you bring it to me please?
 - B: OK [leaves to go get dress].
 - Wait, did I say **green**? / #blue? Sorry, I meant my red dress.

¹⁴ A. Lücking and J. Ginzburg (2022). “How to repair a slip of the tongue?” In: [Proc. of SemDial 2022](#), 35–46




- (13) [...] with a roof over them
- a. ?No, that's [?] not true. The roof (i) is not $\langle * \rangle$ / (ii) actually is $\langle * \rangle$
 - b. ?Wait a minute. The roof (i) is not $\langle * \rangle$ / actually is $\langle * \rangle$



- (13) [...] with a roof over them
- ?No, that's [?] not true. The roof (i) is not $\langle * \rangle$ / (ii) actually is $\langle * \rangle$
 - ?Wait a minute. The roof (i) is not $\langle * \rangle$ / actually is $\langle * \rangle$

- What is *that* referring to? It does not seem to be able to pick out the gesture
 - What can be said in the places marked with the wildcard " $\langle * \rangle$ "? Any verbal answer would violate the parallelism constraint!
- No gesture meaning accessible

(14) [...] with a  roof over them

a. No, that's not true, the roof (i) is not





/ (ii) actually is



- Multimodal repair is possible: categorical parallelism is preserved.
- gestures can respond to gestures

Establishing a linguistic interpretation

(15) a. A: [...] with a  roof over them

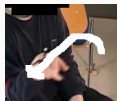
b. B: By , do you mean that (i) the roof is a flat one / (ii) extends to the right?

c. A: Yes.

d. B: But that's not true. The roof (i) is not flat / (ii) does not extend to the right.

- If interlocutors agree on a linguistic interpretation of a gesture, then this interpretation can finally be questioned.
- “The Linguistic Interpretation of Non-emblematic Gestures Must be agreed in Dialogue”¹⁵

¹⁵ A. Lücking, A. Mehler, and A. Henlein (2024). “The Linguistic Interpretation of Non-emblematic Gestures Must be agreed in Dialogue: Combining Perceptual Classifiers and Grounding/Clarification Mechanisms”. In: [Proc. of the 28th Workshop on The Semantics and Pragmatics of Dialogue](#)



- (16) [...] two poles with a roof over them
- They (= two poles) stand firm.
 - It (= roof) was covered in moss.
 - #It (= *gesture*) extends to the right.

- Noun phrases can be picked out by pronouns
- The gesture does not appear to be anaphorically accessible

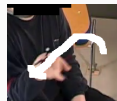
- The linguistic and visual meanings are not on a par and one cannot simply switch from one to the other.
- Accordingly, it is important to keep the two dimensions apart when trying to formalize the semantic integration of speech and gesture.

Visuo-spatial models

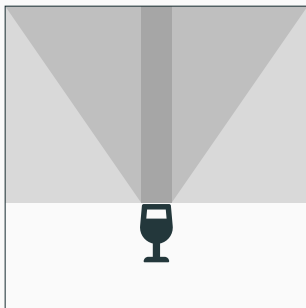
“Visual truth-functions”

- There are at least quite clear semantic intuitions about the circumstances under which a multimodal utterance is true that can guide semantic theorizing.
 - Informally, the multimodal PP is true of the modified NP if the extension $[[NP]]^e$ of the NP in situation e has a roof and the roof “looks like” the gesture.
- The only thing left to do: specify what “look like a gesture” means.

[...] two poles with a roof over them



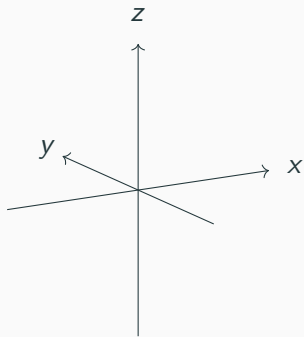
Spatial prepositions



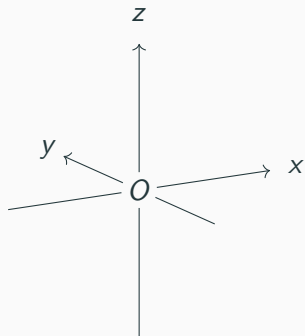
- Three different readings of *above*
 - Each is a sub-region within the space surrounding the reference object
- (Three-dimensional, Euclidean) **Vector Space Semantics**¹⁶

¹⁶ J. Zwarts (1997). "Vectors as Relative Positions: A Compositional Semantics of Modified PPs". In: *J. of Semantics* 14, 57–86

Euclidean space, idea

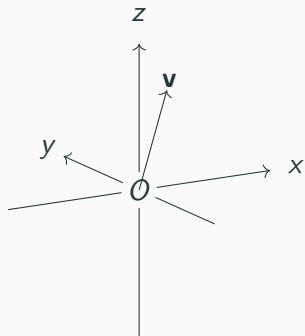


Euclidean space, idea



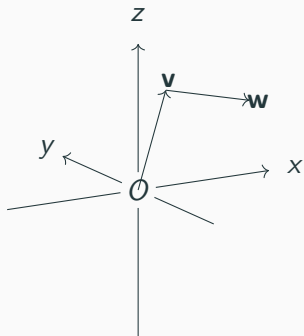
- O : Origin

Euclidean space, idea



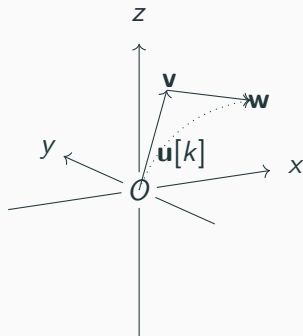
- O : Origin
- \mathbf{v} : Vector

Euclidean space, idea



- O : Origin
- \mathbf{v} : Vector
- \mathbf{w} : Vector
- \mathbf{vw} : Sequence of (two) vectors

Euclidean space, idea



- O : Origin
- \mathbf{v} : Vector
- \mathbf{w} : Vector
- \mathbf{vw} : Sequence of (two) vectors
- $\mathbf{u}[k]$: Path: Sequence of k vectors

- Model: $\langle V, D_e, D_s \rangle$, with
 - V : Interpretation function
 - D_e : Domain of entities
 - D_s : Domain of situations/events

Extending the domain of semantic model¹⁷

- The domain of points: $D_p = V$ (each point is defined by a vector's endpoint)
- The domain of vectors: $D_v = V \times V$ (the Cartesian product of V)

Vector space population: For each element ("point") $w \in D_p$ there is a vector space $V_w \subseteq D_v$ (w is the zero-vector, or origin of V_w).

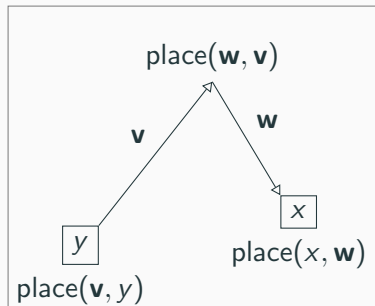
¹⁷ J. Zwarts and Y. Winter (2000). "Vector Space Semantics: A Model-Theoretic Analysis of Locative Prepositions". In: [Journal of Logic, Language, and Information](#) 9, 169–211

D_e (entities), D_s (events)
and D_v (vector
sequences) are related by
a couple of functions:

- The vector space located at a concrete object denoted by an NP α is given by 'space($\llbracket \alpha \rrbracket^e$)'.
- Place and axis vectors determine spatial relationships:
 - place(x, \mathbf{v}): x is placed at the end of \mathbf{v} ; place(\mathbf{v}, x): the starting point of \mathbf{v} is placed at x ; place(\mathbf{u}, \mathbf{v}): the starting point of \mathbf{u} is placed at the end of \mathbf{v} .
 - axis(x, \mathbf{v}) object x has an axis \mathbf{v} .

¹⁸ J. Zwarts (2003). "Vectors Across Spatial Domains: From Place to Size, Orientation, Shape, and Parts". In: [Representing Direction in Language and Space](#). Ed. by E. van der Zee and J. Slack, 39–68, frame

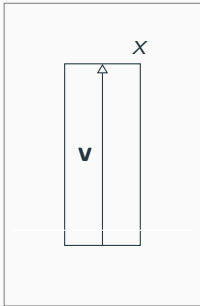
Place



The car is in front of the house.

The spoon is near the fork.

...



The bar is straight.

The tower is wide.

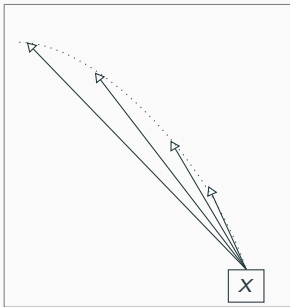
...

(Very simple model, the use of subsidiary axes would lead to much more detailed object shapes.)

- Paths: sequences of axis or place vectors. Paths are defined as n -tuples of points, $n > 2$.
- Paths are notated as $\mathbf{v}[k]$.
- We use the letters a and z to denote the first and the last element of the tuple, respectively. The start of a path is indexed as $\mathbf{v}[a]$, its end point as $\mathbf{v}[z]$.
- Paths can be constructed for axis and for place vectors, giving rise to axis-paths and place-paths, respectively.
- Note that paths are non-temporal entities. They receive a temporal interpretation only if index k is mapped to points or intervals in time.

Note: Paths can be implemented in terms of a vector plus one or more transformation matrices.

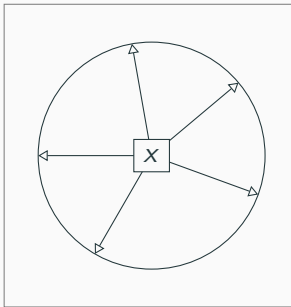
Place path



*The road bends to the left.
She travels along the river bend.*

...

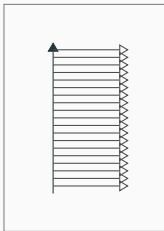
Axis path



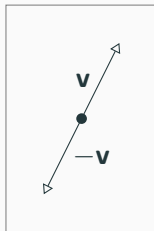
*A round disk.
A cylindric cup.*

...

Vectors pointing in the same direction constitute a **level**.

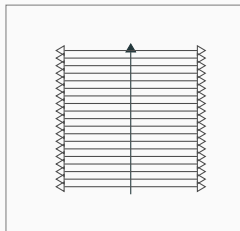


The **inverse** $-\mathbf{v}$ of a vector \mathbf{v} points in the opposite direction of \mathbf{v} .



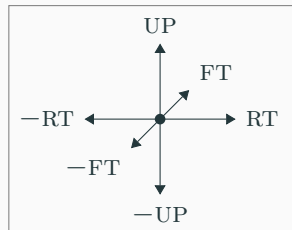
Plane

The set of vectors varying only in the direction of one of their three dimensions (i.e., vectors + their inverses) make up a **plane**.



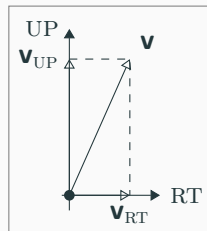
Oriented Vector Space

Each vector space V provides three, mutually perpendicular **orienting levels**. Intuitively, these levels correspond to the directions *up* (UP), *forward* or *front* (FT), and *right* (RT). These levels in addition to their corresponding inverses, give rise to an **oriented vector space**.

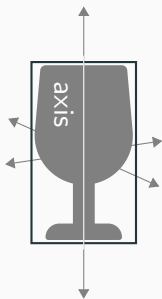


Projections

Given orienting levels A and A' , a vector \mathbf{v} can be decomposed into its **projections** onto the levels, \mathbf{v}_A and \mathbf{v}'_A . The figure shows the orthogonal components of \mathbf{v} on the UP and the RT levels.

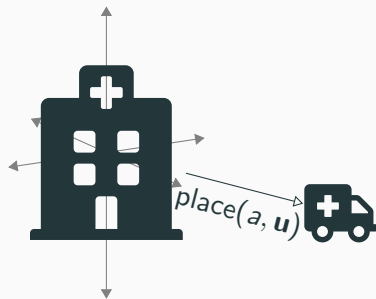


Ex.: Wine glass



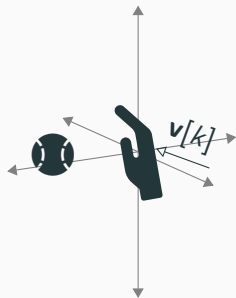
Spatial projection of a wine glass. The glass is located at the center of a vector space, and has a main axis.

Ex.: Near



Spatial projection of two objects being spatially related. The ambulance a is near the hospital if the length of \mathbf{u} is below some threshold τ .

Ex.: Throwing

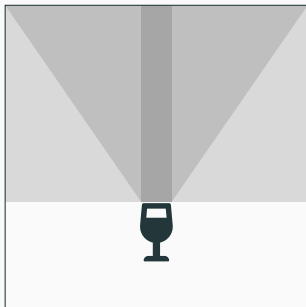


Spatial projection of a throwing event. The movement of the hand “leaves” a place path vector sequence in the domain.

(We will address the issues of handshapes soon.)

Vector spaces in truth-conditional action

- Clear motivation for vectors from modified spatial prepositions such as *3cm above X*.
- But it is reasonable to assume that vectors should extend truth-condition of many more constructions.



- Three readings of *above(wineglass)*:
- $\{\mathbf{v} \in \text{space}(\llbracket \text{wineglass} \rrbracket^e) \mid$
 1. $|\mathbf{v}_{\text{UP}}| = |\mathbf{v}|$ [dark gray]
 2. $|\mathbf{v}_{\text{UP}}| > |\mathbf{v}_{\text{RT}} - \mathbf{v}_{\text{RT}}|$ [medium gray]
 3. $|\mathbf{v}_{\text{UP}}| > 0$ [light gray]

$|\mathbf{v}|$: length of vector \mathbf{v} .

$$|\mathbf{v}| = \sqrt{v_1^2 + v_2^2 + v_3^2}$$

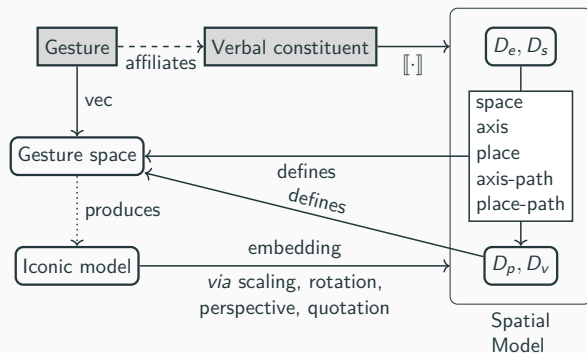
Vectors are not normalized.

Ex.: Walk



- $\lambda x. \lambda e [\text{walk}(e) \wedge \text{ag}(e) = x \wedge \exists \mathbf{v} [\text{path}(e, \mathbf{v})]]$.
- “Mary walked the shortest route from the university to the capitol.” is true if there is an e and an x such that the above holds, and there is no \mathbf{w} which is shorter than \mathbf{v} .

Architecture of spatial gesture semantics



Spatial models relate entities (D_e) and events (D_s) onto points (D_p) and vectors (D_v) in terms of vector spaces, axes, places, and paths. The latter are used to define vectorial gesture spaces. Gestures are translated into these gesture spaces, producing formal iconic models that – eventually modified by the operations of scaling, rotation, perspective, or quotation – impose constraints on the spatial domain in which their affiliated verbal expressions are evaluated.

Very Basic Vector Math

Vectors

- A vector \mathbf{v} is a collection of numbers:
 $\mathbf{v} = [x_0, x_1, x_2, \dots, x_{d-1}]$.
- d is the dimensionality of a vector (note that indexing usually starts with “0”).
- Ex.: $\mathbf{v} = [0, 4, 6]$ is a three-dimensional vector.
- Vectors can be “stretched” by multiplying them with a scalar a (a number).
- $a\mathbf{v} = [ax_0, ax_1, ax_2, \dots, ax_{d-1}]$
- Vectors of the same dimension can be added together by adding their elements (“superposition”).
- $\mathbf{v} + \mathbf{w} = [x_0 + y_0, x_1 + y_1, x_2 + y_2, \dots, x_{d-1} + y_{d-1}]$

Length and Norm

- The length of a vector is the square root of the sum of the squares of its elements.
- $|\mathbf{v}| = \sqrt{x_0^2 + x_1^2 + x_2^2 + \dots + x_{d-1}^2}$
(also written $||\mathbf{v}||$)
- Normalized or unit vectors are vectors of length 1.
- The unit vector of a vector \mathbf{v} is obtained by dividing \mathbf{v} by $|\mathbf{v}|$.
- $\hat{\mathbf{v}} = \frac{\mathbf{v}}{|\mathbf{v}|} = \left[\frac{x_0}{|\mathbf{v}|}, \frac{x_1}{|\mathbf{v}|}, \frac{x_2}{|\mathbf{v}|}, \dots, \frac{x_{d-1}}{|\mathbf{v}|} \right]$

Linear Transformations

- A linear mapping of a vector is defined in terms of a set of vectors collected in a matrix.

- A 2×2 -dimensional matrix is

$$\mathbf{M} = \begin{bmatrix} m_{1,1} & m_{1,2} \\ m_{2,1} & m_{2,2} \end{bmatrix}$$

- A linear transformation of a two-dimensional vector \mathbf{v} is $\begin{bmatrix} y_0 \\ y_1 \end{bmatrix} = \begin{bmatrix} m_{1,1} & m_{1,2} \\ m_{2,1} & m_{2,2} \end{bmatrix} \cdot \begin{bmatrix} x_0 \\ x_1 \end{bmatrix}$

- $\mathbf{M}\mathbf{v} = \begin{bmatrix} m_{1,1} & m_{1,2} \\ m_{2,1} & m_{2,2} \end{bmatrix} \cdot \begin{bmatrix} x_0 \\ x_1 \end{bmatrix} = \begin{bmatrix} m_{1,1}x_0 + m_{1,2}x_1 \\ m_{2,1}x_0 + m_{2,2}x_1 \end{bmatrix}$

- Ex.: Counterclockwise rotation by θ° .

- $\mathbf{M} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$